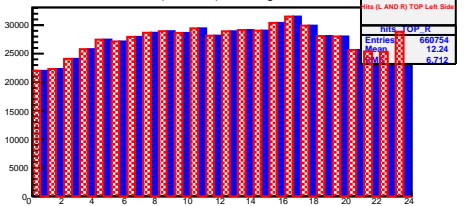
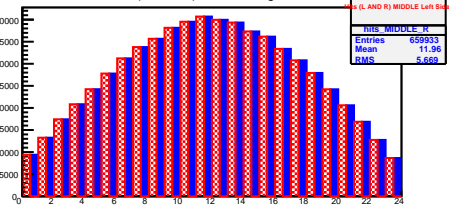


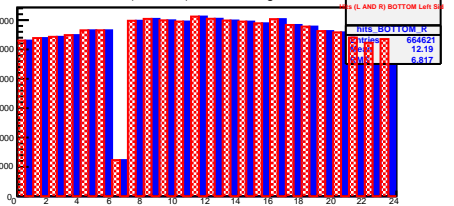
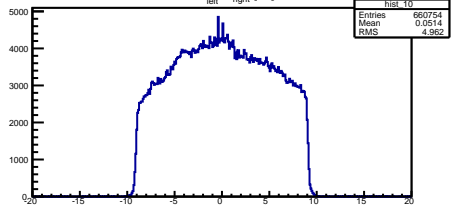
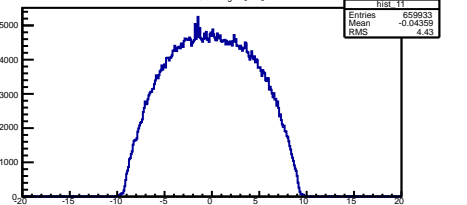
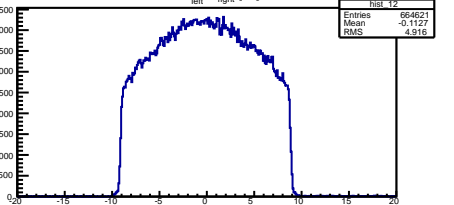
Hits (L AND R) TOP Right Side



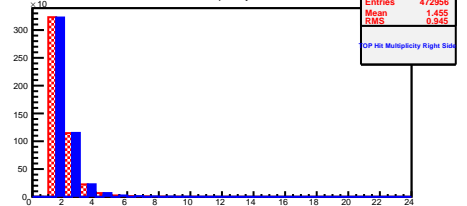
Hits (L AND R) MIDDLE Right Side



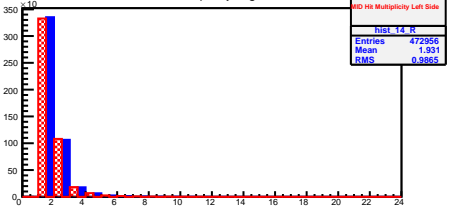
Hits (L AND R) BOTTOM Right Side

TOP T<sub>left</sub>-T<sub>right</sub> [ns]MID T<sub>left</sub>-T<sub>right</sub> [ns]BOT T<sub>left</sub>-T<sub>right</sub> [ns]

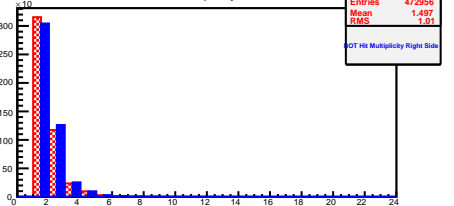
TOP Hit Multiplicity Left Side



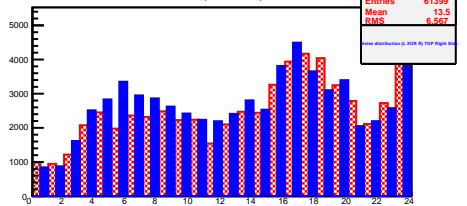
MID Hit Multiplicity Right Side



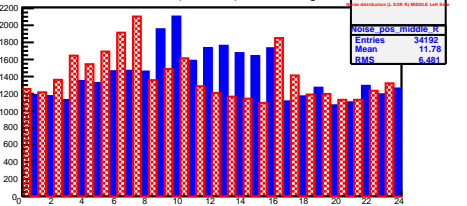
BOT Hit Multiplicity Left Side



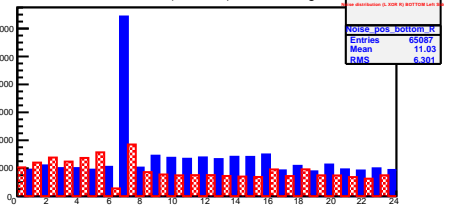
Noise distribution (L XOR R) TOP Left Side



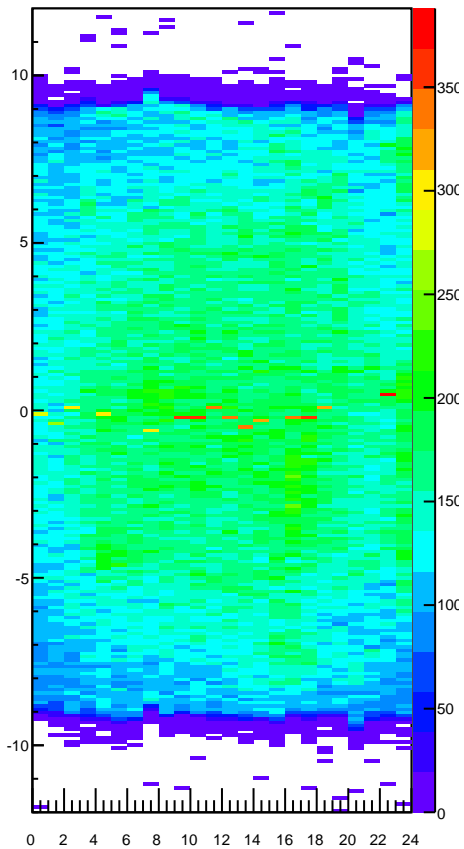
Noise distribution (L XOR R) MIDDLE Right Side



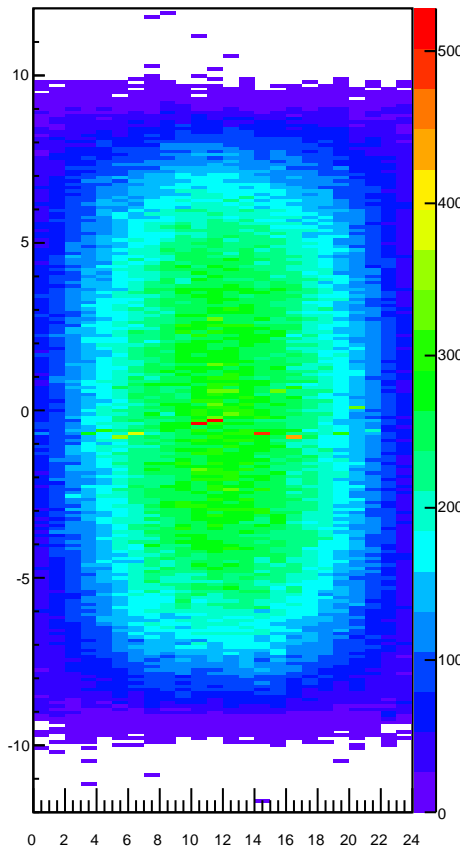
Noise distribution (L XOR R) BOTTOM Right Side



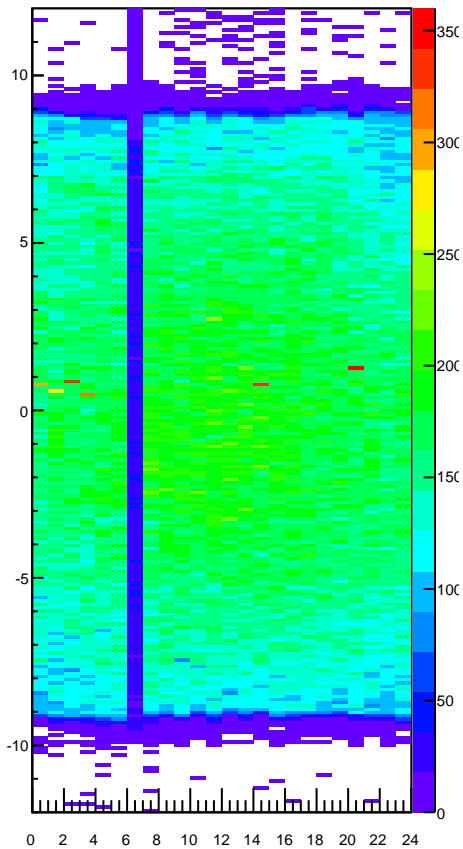
TOP Hits profile plot

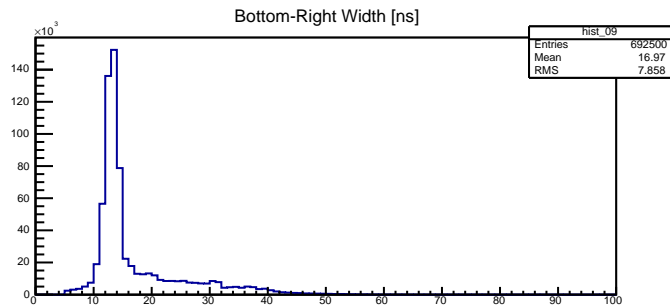
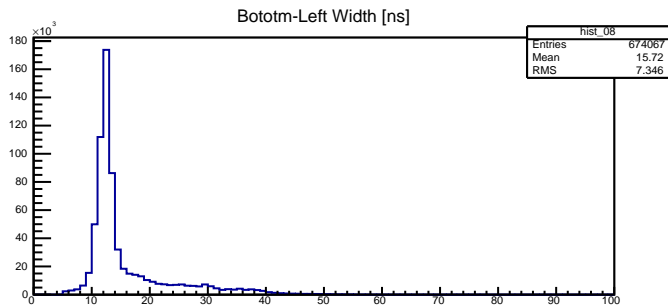
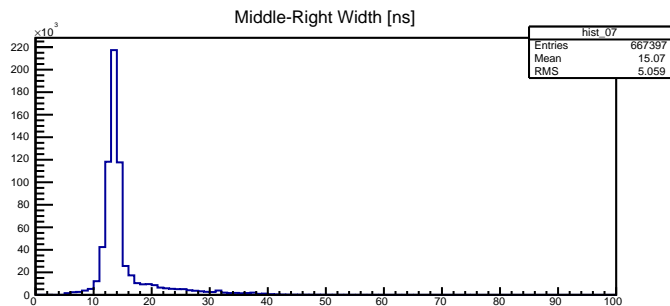
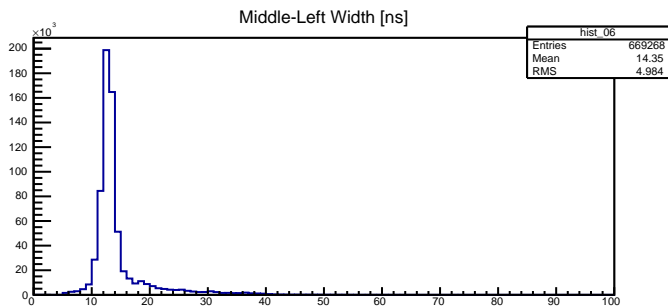
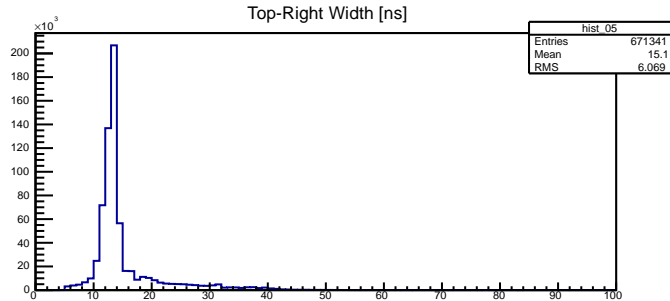
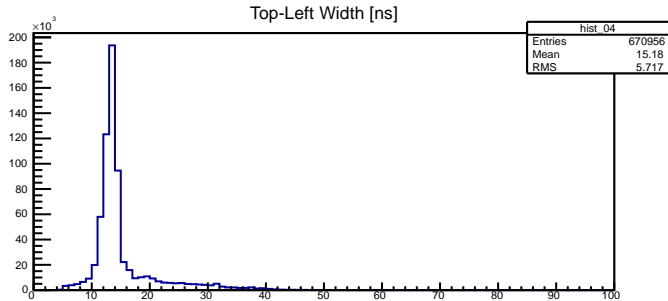


MID Hits profile plot

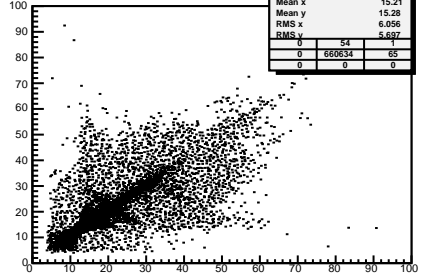


BOT Hits profile plot

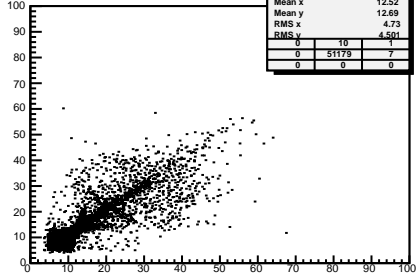




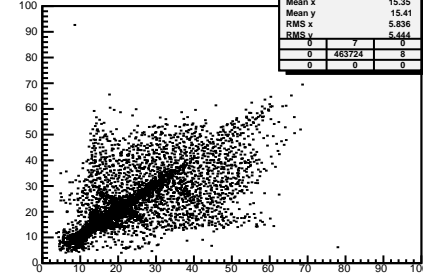
L vs R widths [ns] - TOP



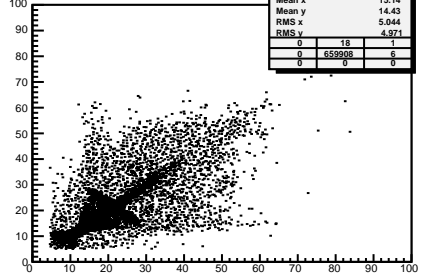
L vs R widths [ns] - TOP



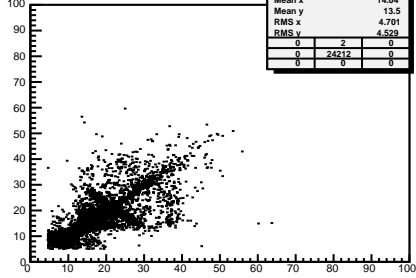
L vs R widths [ns] - TOP



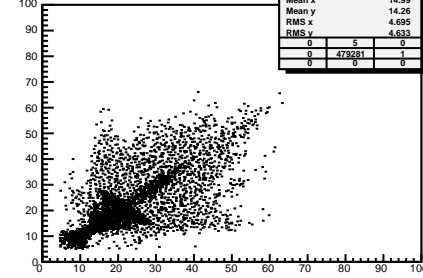
L vs R widths [ns] - MID



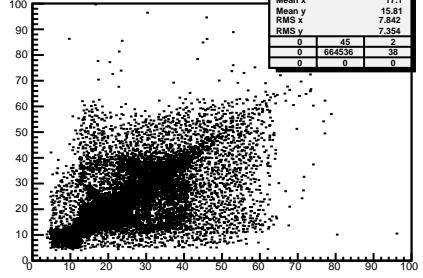
L vs R widths [ns] - MID



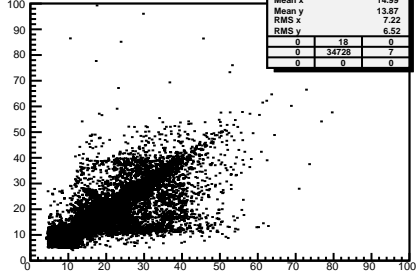
L vs R widths [ns] - MID



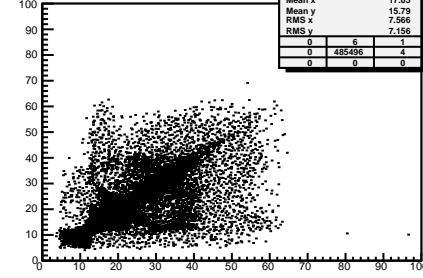
L vs R widths [ns] - BOT



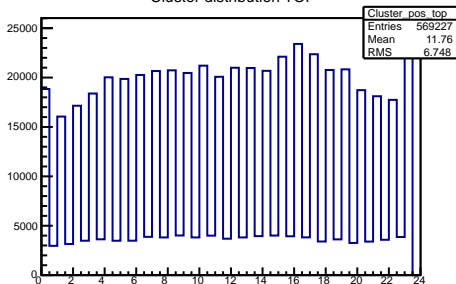
L vs R widths [ns] - BOT



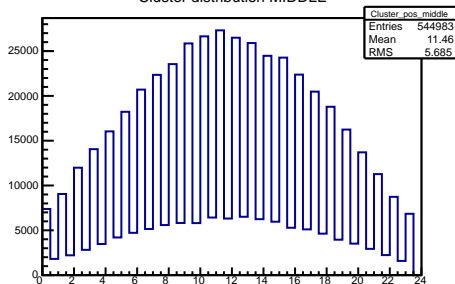
L vs R widths [ns] - BOT



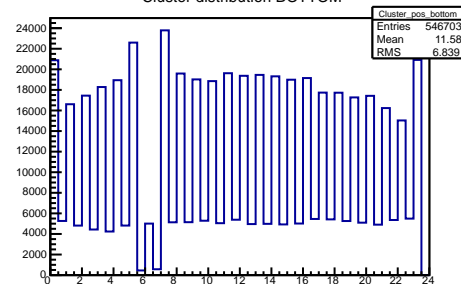
Cluster distribution TOP



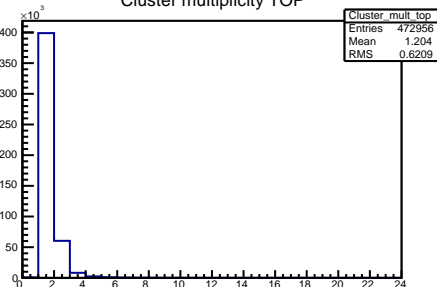
Cluster distribution MIDDLE



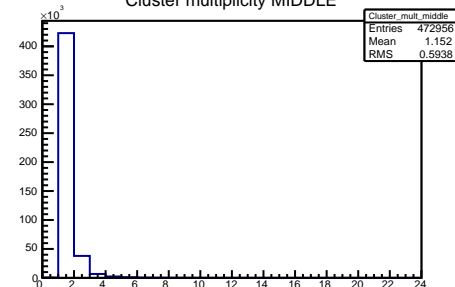
Cluster distribution BOTTOM



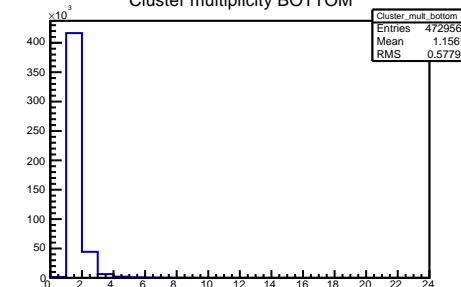
Cluster multiplicity TOP



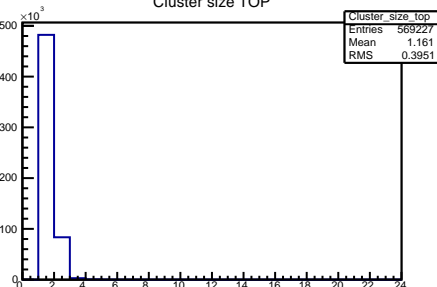
Cluster multiplicity MIDDLE



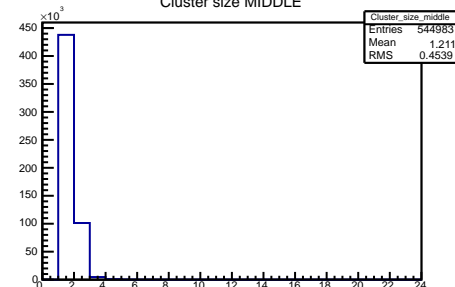
Cluster multiplicity BOTTOM



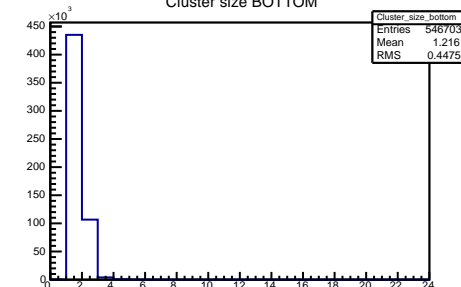
Cluster size TOP



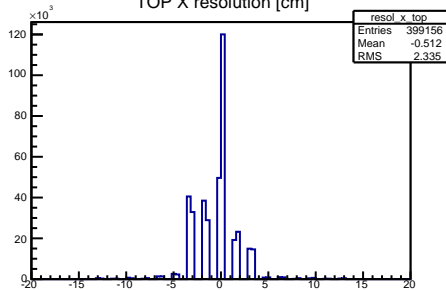
Cluster size MIDDLE



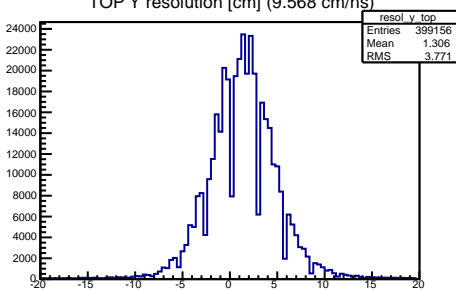
Cluster size BOTTOM



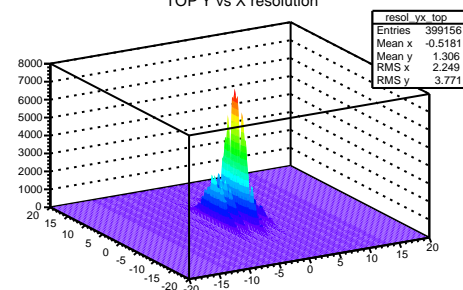
TOP X resolution [cm]



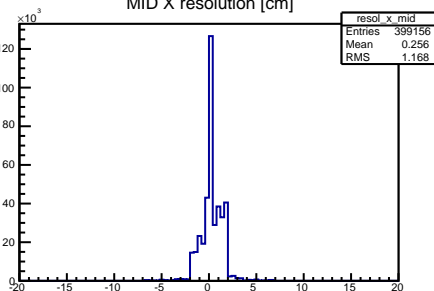
TOP Y resolution [cm] (9.568 cm/ns)



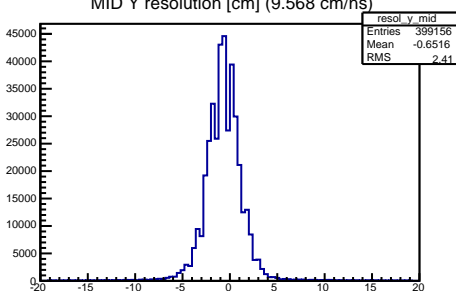
TOP Y vs X resolution



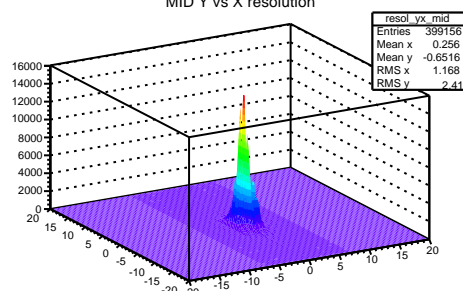
MID X resolution [cm]



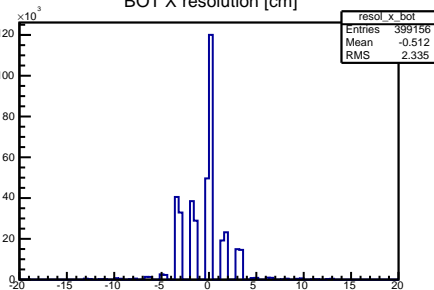
MID Y resolution [cm] (9.568 cm/ns)



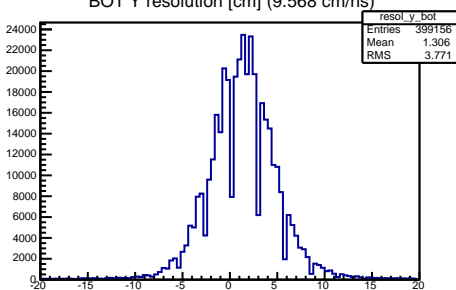
MID Y vs X resolution



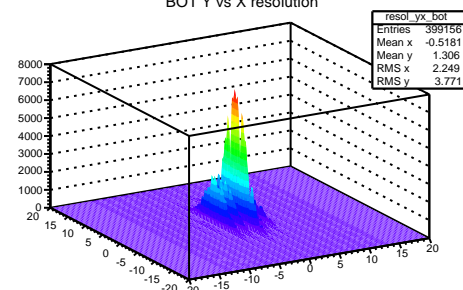
BOT X resolution [cm]



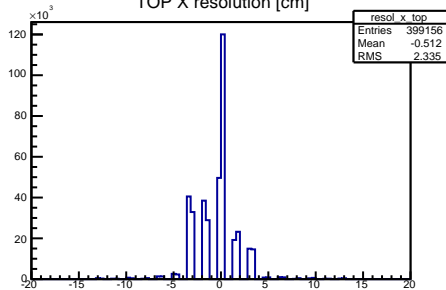
BOT Y resolution [cm] (9.568 cm/ns)



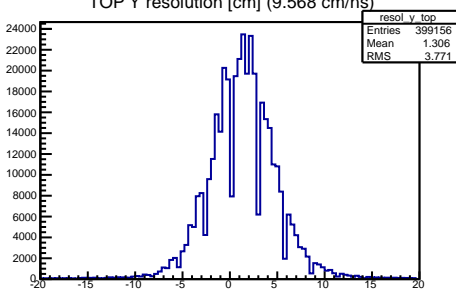
BOT Y vs X resolution



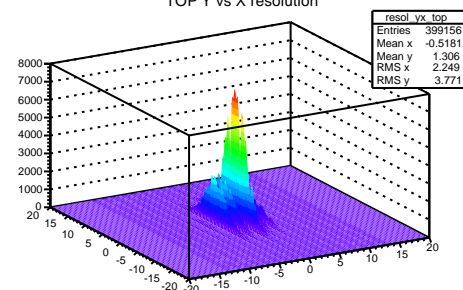
TOP X resolution [cm]



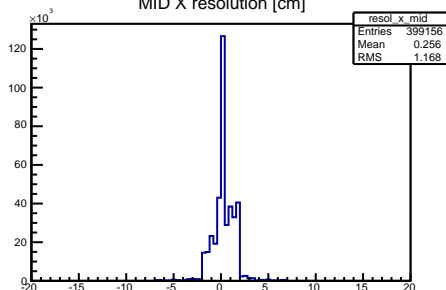
TOP Y resolution [cm] (9.568 cm/ns)



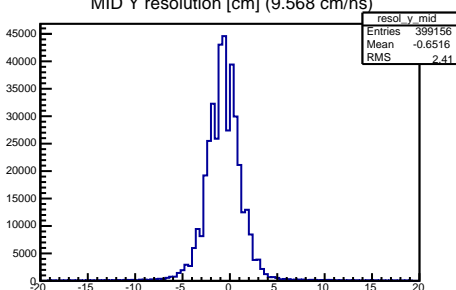
TOP Y vs X resolution



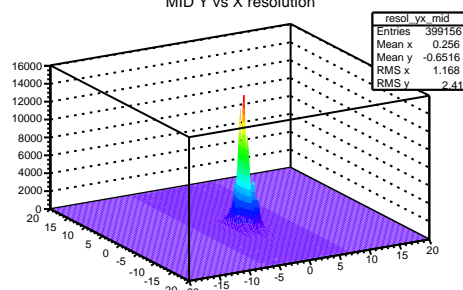
MID X resolution [cm]



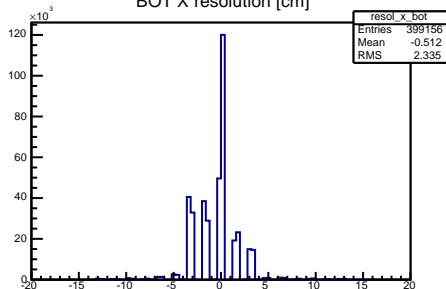
MID Y resolution [cm] (9.568 cm/ns)



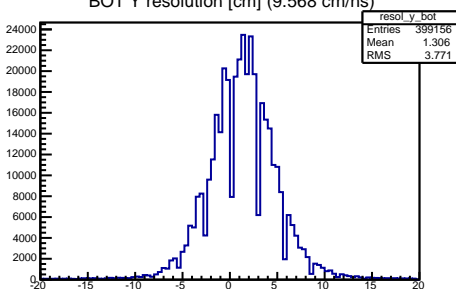
MID Y vs X resolution



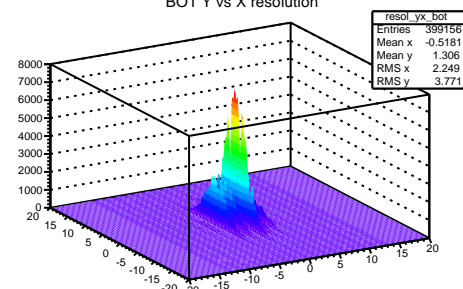
BOT X resolution [cm]



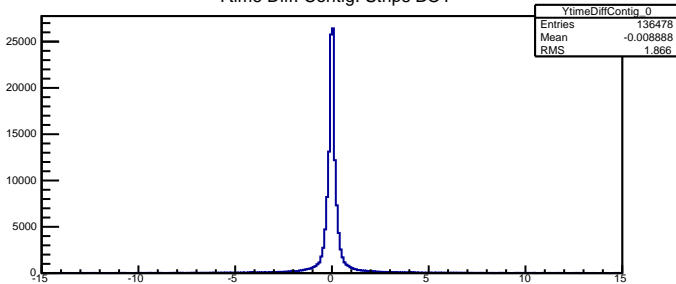
BOT Y resolution [cm] (9.568 cm/ns)



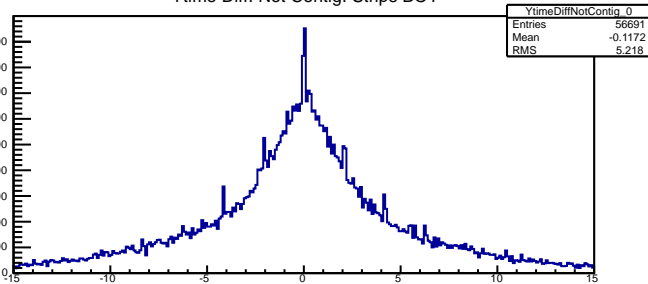
BOT Y vs X resolution



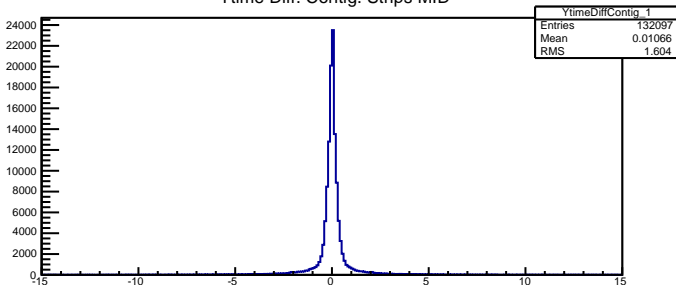
Ytime Diff. Contig. Strips BOT



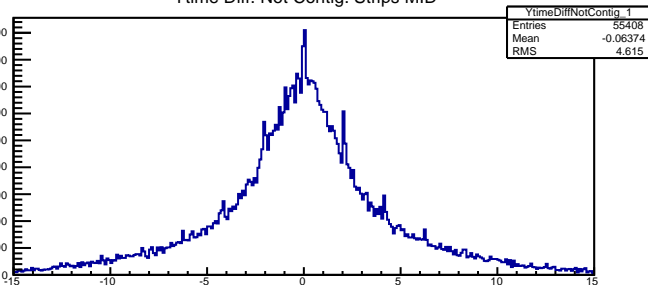
Ytime Diff. Not Contig. Strips BOT



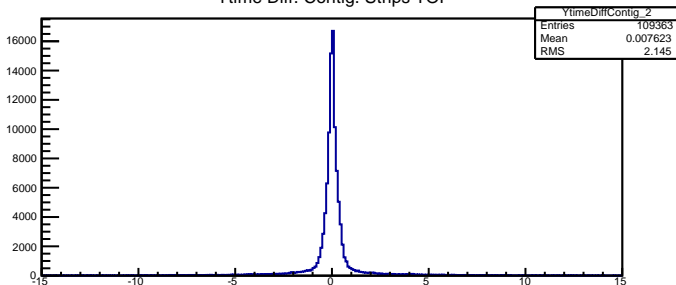
Ytime Diff. Contig. Strips MID



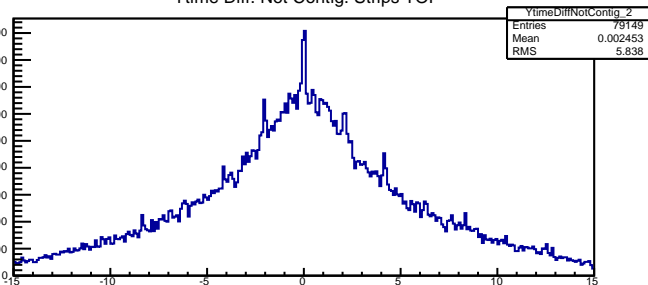
Ytime Diff. Not Contig. Strips MID



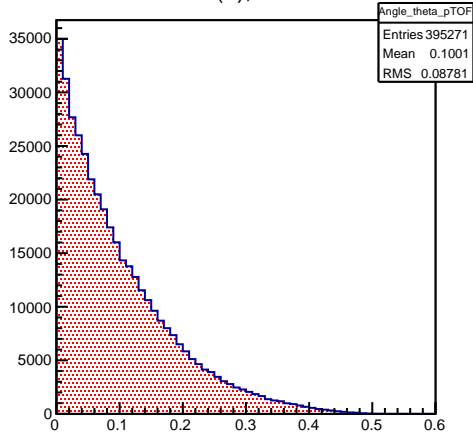
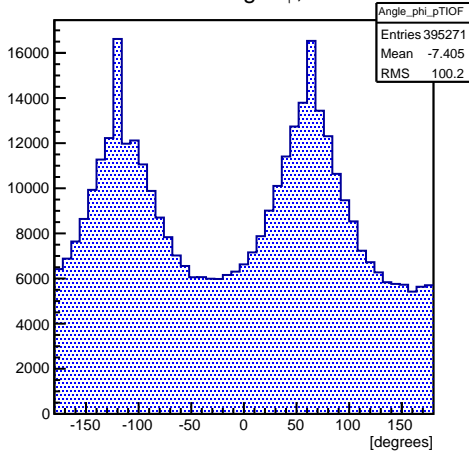
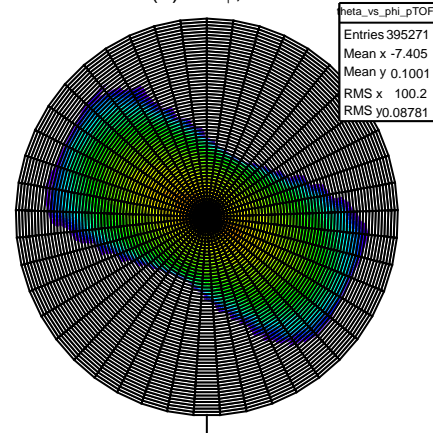
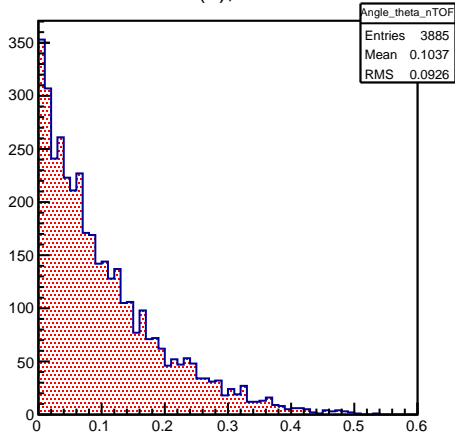
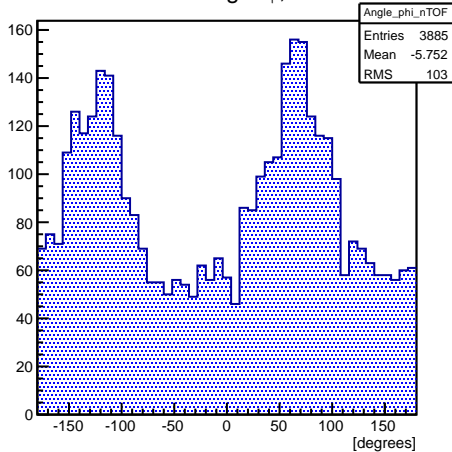
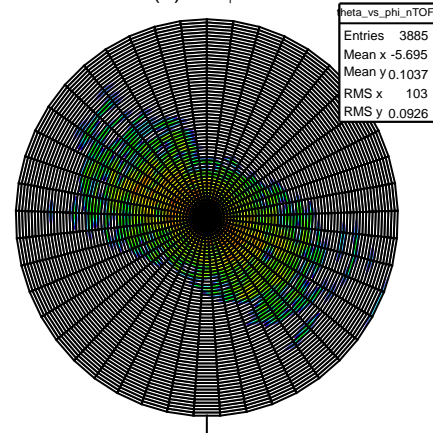
Ytime Diff. Contig. Strips TOP



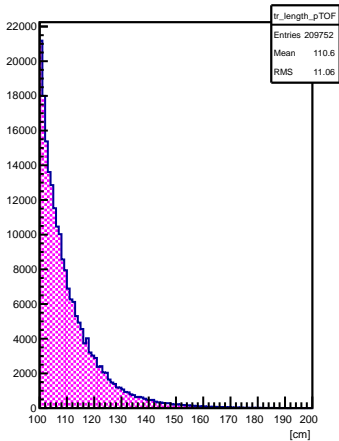
Ytime Diff. Not Contig. Strips TOP



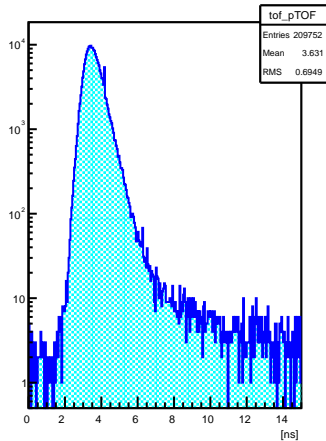


1-cos( $\theta$ ), TOF>0Azimuthal angle  $\phi$ , TOF>01-cos( $\theta$ ) vs.  $\phi$ , TOF>01-cos( $\theta$ ), TOF<0Azimuthal angle  $\phi$ , TOF<01-cos( $\theta$ ) vs.  $\phi$  TOF<0

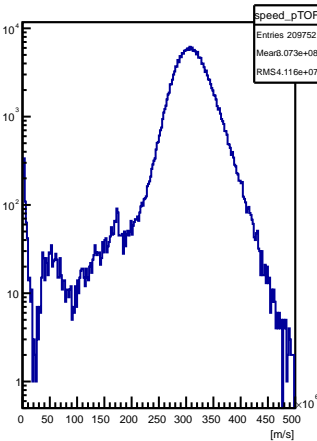
Track length, TOF&gt;0



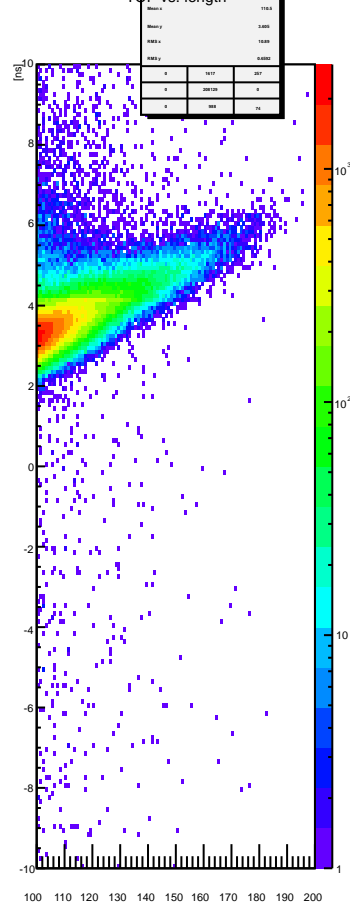
Time of flight, TOF&gt;0



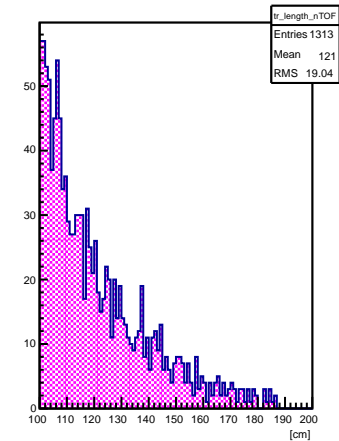
Particle speed, TOF&gt;0



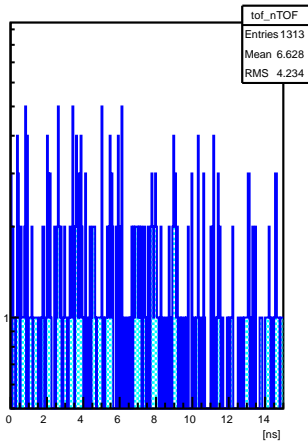
TOF vs. length



Track length, TOF&lt;0



Time of flight, TOF&lt;0



Particle speed, TOF&lt;0

